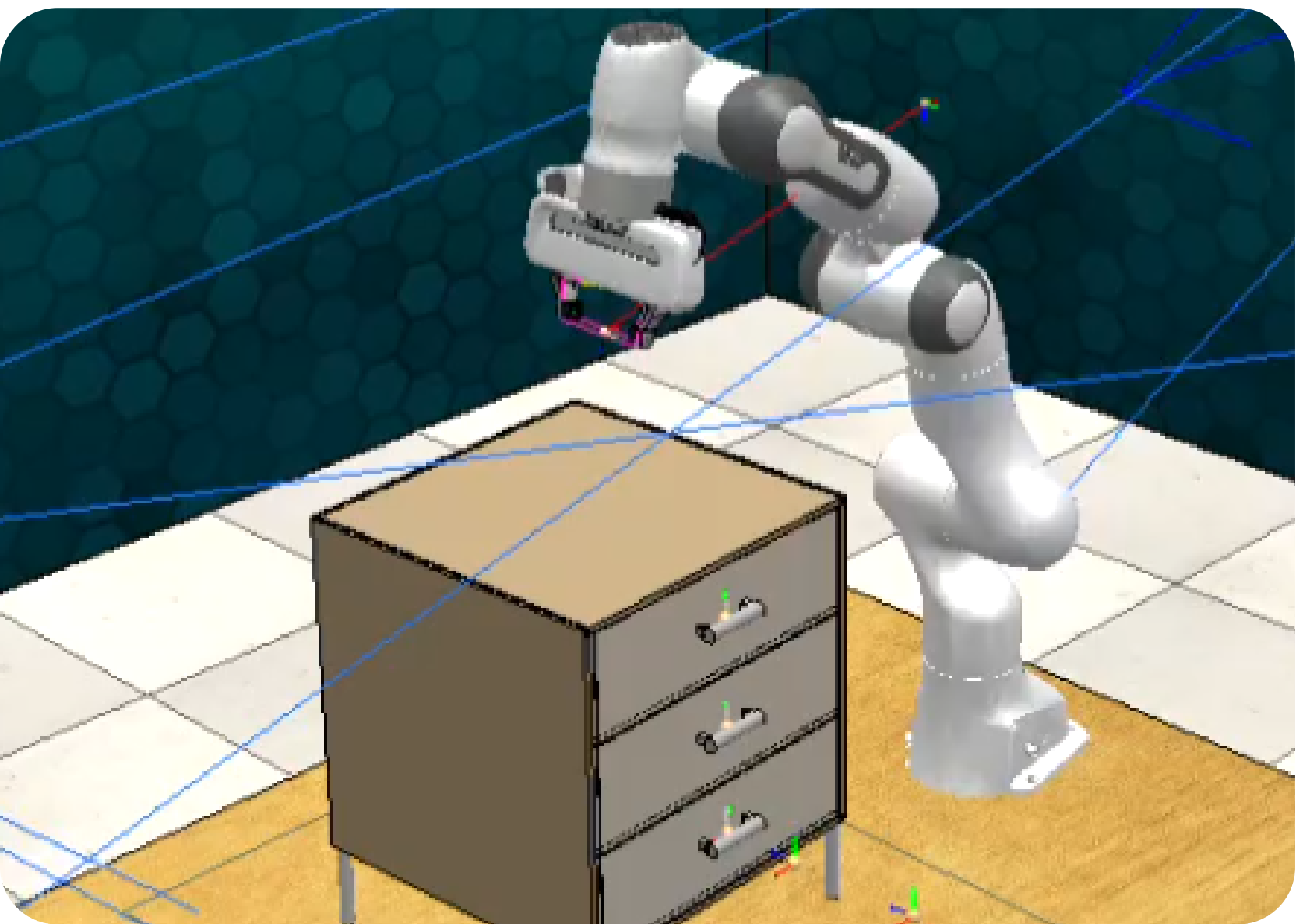




You are a Franka robot using end-effector control.  
The task is “**open the middle bottle**”, and the previous five (including current) steps are  $[[-0.1060, 0.1280, -0.0767, \dots]]$ .  
Can you predict the 2-D visual trace of the end effector and the action of the next 1 step?



I couldn't find a **bottle** in the current scene.  
Do you mean the **middle drawer** instead?

